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1	BRS	L1	788728	(match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4) same (attitude or position\$3 or posture\$1 or orientation\$1 or pose\$1 or location\$1)	USPAT	2005/08/03 16:37	
2	BRS	L2	218099	1 same (boundar\$3 or edge\$1 or border\$1 or line\$1)	USPAT	2005/08/03 15:56	
3	BRS	L3	54717	2 same (template\$1 or model\$1 or submodel\$1 or sub-model\$1 or reference\$1 or stored or database or known)	USPAT	2005/08/03 16:01	
4	BRS	L4	972	3 same((high\$3 or low\$3 or small\$3 or big\$4 or maxim\$6 or minm\$6 or increas\$3 or decreas\$3 or increment or decrement) near\$5 (resolution\$1 or size\$1))	USPAT	2005/08/03 16:23	
5	BRS	L5	783	4 same (graph\$5 or curv\$5 or polygon\$2 or line\$1 or geometr\$5 or imag\$3)	USPAT	2005/08/03 14:06	
6	BRS	L6	540	3 same((high\$3 or big\$4 or maxim\$6 or increas\$3 or increment or enlarg\$5) near\$5 (resolution\$1 or size\$1))	USPAT	2005/08/03 14:07	

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7	BRS	L7	565	3 same((low\$3 or small\$3 or minm\$6 or decreas\$3 or decrement) near5 (resolution\$1 or size\$1))	USPAT	2005/08/03 14:09	
8	BRS	L8	106	6 same((low\$3 or small\$3 or minm\$6 or decreas\$3 or decrement) near5 (resolution\$1 or size\$1))	USPAT	2005/08/03 14:09	
9	BRS	L9	249644	((match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4) near5 (graph\$5 or curv\$5 or polygon\$2 or line\$1 or geometr\$5 or imag\$3))	USPAT	2005/08/03 14:11	
10	BRS	L10	92	7 same ((match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4) near5 (graph\$5 or curv\$5 or polygon\$2 or line\$1 or geometr\$5 or imag\$3))	USPAT	2005/08/03 16:20	

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11	BRS	L11	25	8 same ((match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4) near5 (graph\$5 or curv\$5 or polygon\$2 or line\$1 or geometr\$5 or imag\$3))	USPAT	2005/08/03 16:01	
12	BRS	L12	282564	((estimat\$4 or approximat\$4 or determin\$4 or judg\$4 or predict\$4) near3 (attitude or position\$3 or posture\$1 or orientation\$1 or pose\$1 or location\$1))	USPAT	2005/08/03 14:15	
13	BRS	L13	66685	12 same (boundar\$3 or edge\$1 or border\$1 or line\$1)	USPAT	2005/08/03 14:16	
14	BRS	L14	3740	13 same ((correct or accurat\$1 or true or errorless or exact or precise) near3 (attitude or position\$3 or posture\$1 or orientation\$1 or pose\$1 or location\$1))	USPAT	2005/08/03 14:19	
15	BRS	L15	17	13 same ((correct or accurat\$1 or true or errorless or exact or precise) near3 (attitude or pose\$1))	USPAT	2005/08/03 15:55	

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16	IS&R	L16	3250	(382/103,151,195,199,203,209,291,299).CCLS.	USPAT	2005/08/03 15:54	
17	IS&R	L17	477	(348/169).CCLS.	USPAT	2005/08/03 15:54	
18	BRS	L18	5234	((estimat\$4 or approximat\$4 or determin\$3 or comput\$3 or calculat\$4 or evaluat\$4 or correct or accurat\$1 or true or errorless or exact or precise) near\$3 (attitude or pose\$1))	USPAT	2005/08/03 16:18	
19	BRS	L19	724	18 same (match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4)	USPAT	2005/08/03 16:11	
20	BRS	L20	129	19 same (boundar\$3 or edge\$1 or border\$1 or line\$1 or outline\$1)	USPAT	2005/08/03 16:19	
21	BRS	L21	3	20 same resolution\$1	USPAT	2005/08/03 15:56	
22	BRS	L22	119	20 same (graph\$5 or curv\$5 or polygon\$2 or line\$1 or geometri\$5 or imag\$3)	USPAT	2005/08/03 16:01	
23	BRS	L23	64	22 same (template\$1 or model\$1 or submodel\$1 or sub-model\$1 or reference\$1 or stored or database or known)	USPAT	2005/08/03 16:02	

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24	BRS	L24	9	16 and 23	USPAT	2005/08/03 16:05	
25	BRS	L26	29232	((geometr\$4 or graph\$4) near3 (match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4))	USPAT	2005/08/03 16:07	
26	BRS	L27	218	26 same (pose or (orientation adj position\$3) or translation or posture or attitude)	USPAT	2005/08/03 16:09	
27	BRS	L28	5	27 same resolution\$1	USPAT	2005/08/03 16:08	
28	BRS	L29	1575	((refin\$5 or smooth\$4 or clear or clarif\$6) near7 (pose or (orientation adj position\$3) or translation or posture or attitude))	USPAT	2005/08/03 16:20	
29	BRS	L30	66	29 same (resolution\$1 or size\$1)	USPAT	2005/08/03 16:14	
30	BRS	L31	19	30 same (match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4)	USPAT	2005/08/03 16:11	
31	BRS	L32	1	16 and 31	USPAT	2005/08/03 16:14	
32	IS&R	L33	219	(358/1.5).CCLS.	USPAT	2005/08/03 16:14	

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33	BRS	L34	96	29 same (resolution\$1 or size\$1 or scal\$3)	USPAT	2005/08/03 16:15	
34	BRS	L35	3	16 and 34	USPAT	2005/08/03 16:15	
35	BRS	L36	20533	(resolution\$1 or size\$1 or scal\$3) same (pose or posture or (position\$3 near1 orientation\$1) or translation)	USPAT	2005/08/03 16:38	
36	BRS	L37	3503	36 same (boundar\$3 or edge\$1 or border\$1 or line\$1 or outline\$1)	USPAT	2005/08/03 16:19	
37	BRS	L38	103	37 same ((match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4) near5 (graph\$5 or curv\$5 or polygon\$2 or line\$1 or geometr\$5 or imag\$3))	USPAT	2005/08/03 16:20	
38	BRS	L40	14	38 same((high\$3 or low\$3 or small\$3 or big\$4 or maxim\$6 or minm\$6 or increas\$3 or decreas\$3 or increment or decrement) near5 (resolution\$1 or size\$1 or scal\$3))	USPAT	2005/08/03 16:24	
39	BRS	L41	176	((estimat\$4 or approxim\$4) near3 pose)	USPAT	2005/08/03 16:37	

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40	BRS	L42	71	41 same (match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4) same (attitude or position\$3 or posture\$1 or orientation\$1 or pose\$1 or location\$1)	USPAT	2005/08/03 16:38	
41	BRS	L43	71	41 same (match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4)	USPAT	2005/08/03 16:38	
42	BRS	L44	17	43 same (resolution\$1 or size\$1 or scal\$3)	USPAT	2005/08/03 16:40	




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IEEE JNL IEE Journal or Magazine

IEEE CNF IEEE Conference Proceeding

IEEE CNF IEE Conference Proceeding

IEEE STD IEEE Standard

- |                          |   |
|--------------------------|---|
| <input type="checkbox"/> | <b>1. Comparative study of coarse head pose estimation</b><br>Brown, L.M.; Ying-Li Tian;<br>Motion and Video Computing, 2002. Proceedings. Workshop on<br>5-6 Dec. 2002 Page(s):125 - 130<br>Digital Object Identifier 10.1109/MOTION.2002.1182224<br><a href="#">AbstractPlus</a>   Full Text: <a href="#">PDF</a> (477 KB) IEEE CNF   |
| <input type="checkbox"/> | <b>2. Operator-theoretic and computational approaches to ill-posed problems in antenna theory</b><br>Nashed, M.;<br>Antennas and Propagation, IEEE Transactions on [legacy, pre - 1988]<br>Volume 29, Issue 2, Mar 1981 Page(s):220 - 231<br><a href="#">AbstractPlus</a>   Full Text: <a href="#">PDF</a> (1360 KB) IEEE JNL   |
| <input type="checkbox"/> | <b>3. Using a scale: self-calibration of a robot system with a factor method</b><br>Hanqi Zhuang; Yan Meng;<br>Robotics and Automation, 2001. Proceedings 2001 ICRA. IEEE International C<br>Volume 3, 2001 Page(s):2797 - 2803 vol.3<br>Digital Object Identifier 10.1109/ROBOT.2001.933046<br><a href="#">AbstractPlus</a>   Full Text: <a href="#">PDF</a> (536 KB) IEEE CNF |
| <input type="checkbox"/> | <b>4. A scale adaptive method for focusing spectral peaks</b><br>Ribeiro, E.; Hancock, E.R.;<br>Pattern Recognition, 2000. Proceedings. 15th International Conference on<br>Volume 3, 3-7 Sept. 2000 Page(s):119 - 122 vol.3<br>Digital Object Identifier 10.1109/ICPR.2000.903499<br><a href="#">AbstractPlus</a>   Full Text: <a href="#">PDF</a> (416 KB) IEEE CNF           |
| <input type="checkbox"/> | <b>5. Detection of stellate distortions in mammograms</b><br>Karssemeijer, N.; te Brake, G.M.;<br>Medical Imaging, IEEE Transactions on<br>Volume 15, Issue 5, Oct. 1996 Page(s):611 - 619<br>Digital Object Identifier 10.1109/42.538938<br><a href="#">AbstractPlus</a>   <a href="#">References</a>   Full Text: <a href="#">PDF</a> (2644 KB) IEEE JNL                      |
| <input type="checkbox"/> | <b>6. Recognition and pose estimation of unoccluded three-dimensional object from a<br/>dimensional perspective view by banks of neural networks</b>  |


Khotanzad, A.; Liou, J.J.-H.;  
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- ☐ **10. Object recognition and pose estimation for robotic manipulation using co-occurrence histograms**  
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- ☐ **13. A study on the flexible camera calibration method using a grid type frame line widths**  
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- ☐ **15. Adapting scale by minimising spectral defocusing for shape from texture**  
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- ☐ **16. An integrated face detection and recognition system**  
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- ☐ **19. High resolution image classification with features from wavelet frames**  
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- ☐ **24. A microprocessor-based spatial-locating system for use with diagnostic**  
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- ☐ **25. Community dialog technology**  
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- ☐ 2. **Geometry-based automatic object localization and 3-D pose detection**  
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- ☐ 4. **A new fractal zerotree coding for wavelet image**  
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- ☐ 5. **Reconstruction of myocardial architecture at high resolution using diffus**  
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